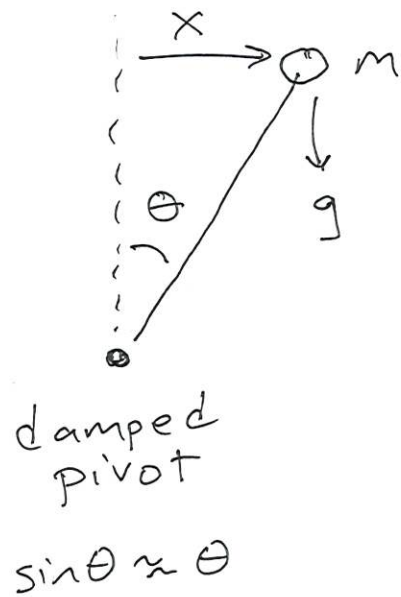
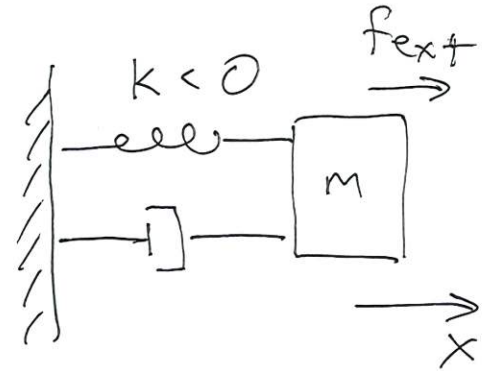


# Control of an inverted pendulum



→ by small angle approx, this is a linear equivalent →



$$m\ddot{x} = -kx - b\dot{x}$$

$$m\ddot{x} + b\dot{x} + kx = 0$$

$$4\ddot{x} + 8\dot{x} - 12x = 0$$

$$\ddot{x} + 2\dot{x} - 3x = 0$$

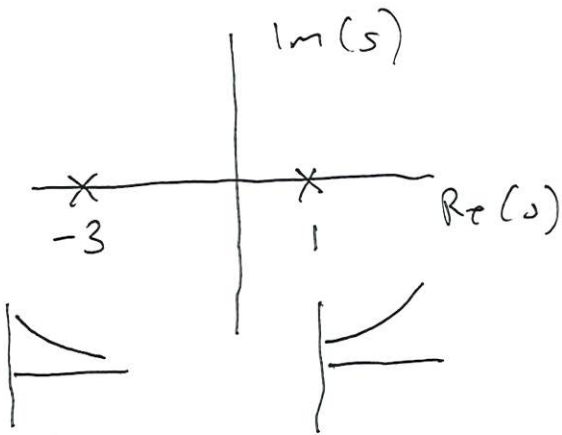
$$s^2 + 2s - 3 = 0 \quad \text{char eq}$$

$$(s+3)(s-1) = 0$$

$$m = 4$$

$$b = 8$$

$$k = -12$$



unstable solution grows with time

use a motor to apply a force, try a virtual spring  
 (P) proportional controller  $f_{ext} = -K_p x$   
 gain

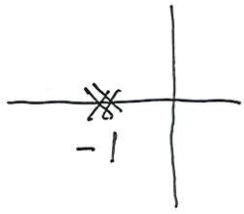
$$4\ddot{x} + 8\dot{x} + (K_p - 12)x = 0$$

$$s^2 + 2s + \left(\frac{K_p}{4} - 3\right) = 0 \quad \text{char eq}$$

goal: critical damping

$$s^2 + 2s + \left(\frac{K_p}{4} - 3\right) = 0 = (s+a)(s+a) = (s+a)^2 = s^2 + 2as + a^2$$

$$a=1, \quad \frac{K_p}{4} - 3 = 1 \rightarrow K_p = 16$$

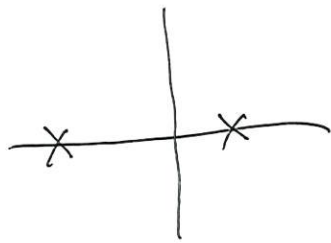


$$s^2 + 2s + \left(\frac{K_p}{4} - 3\right) = s^2 + 2\zeta\omega_n s + \omega_n^2$$

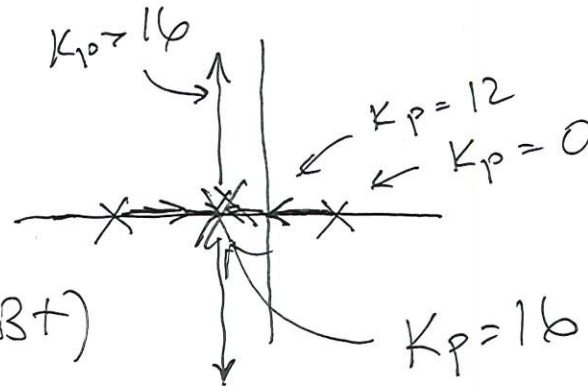
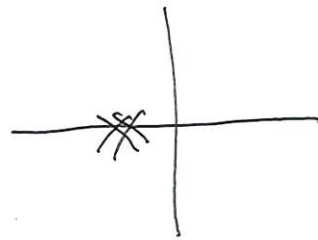
$\zeta = 1$  for critical damping

so  $\omega_n = 1, K_p = 16$

Before



After



for  $K_p = 16, x(t) = e^{-t}(A+Bt)$

time constant  $\tau = \left| \frac{1}{c} \right| = 1 \text{ sec}$

To improve performance:  $f_{ext} = -K_p x - K_D \dot{x}$  PD control

derivative control

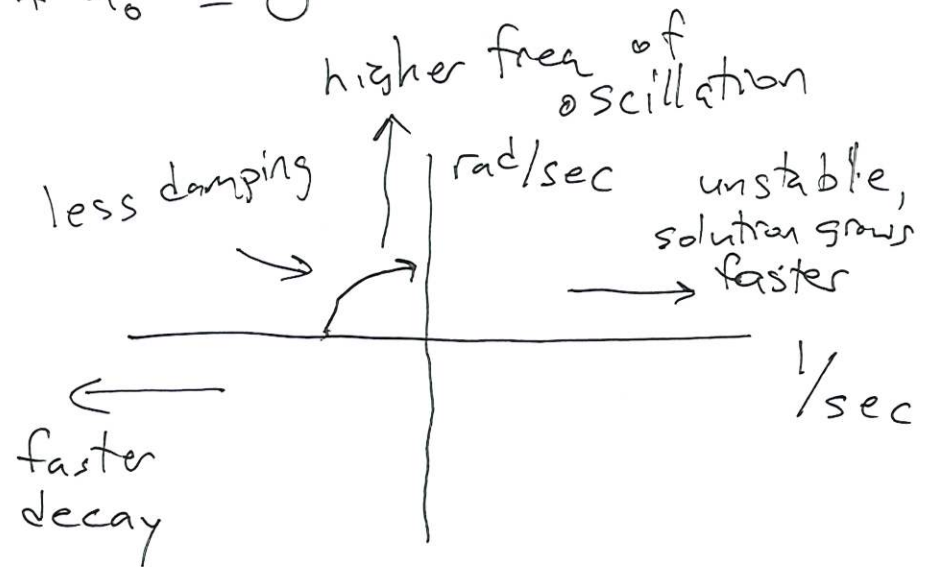
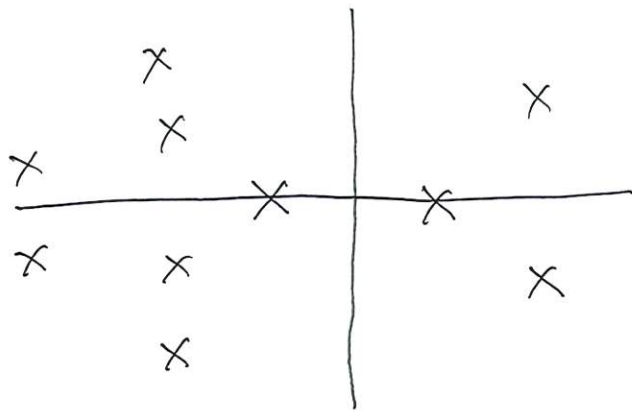
2 gains to play with, 2 roots, put roots anywhere

virtual damper

$n^{\text{th}}$  - order char eq

$$s^n + a_{n-1}s^{n-1} + \dots + a_1s + a_0 = 0$$

$n$  roots



Each comp conj pair:  $e^{ct} (A \cos dt + B \sin dt)$

real root:  $A e^{ct}$

repeated real root:  $B t e^{ct}$

2:  $e^{ct} (A + B t)$

For stable underdamped  $2^{\text{nd}}$  - order:

$$c \pm d j$$

$$c = -\gamma \omega_n$$

$$d = \omega_d = \omega_n \sqrt{1 - \gamma^2}$$

$$\omega_n = \sqrt{c^2 + d^2}$$

Your feedback needed! What works, what could be better?

**Class format:** Handwritten notes posted later as pdfs, lecture videos, occasional concept questions for discussion, shorter yell-out-your-answer questions

**Web textbook:** Are you reading/consulting it?

**Homework:** Helping you learn?

**Discussion session:** If you go, do you find it useful? Feedback for TAs?

**Office hours:** Helpful? Too crowded?

**Other?**