

NRF24L01 + Introduction

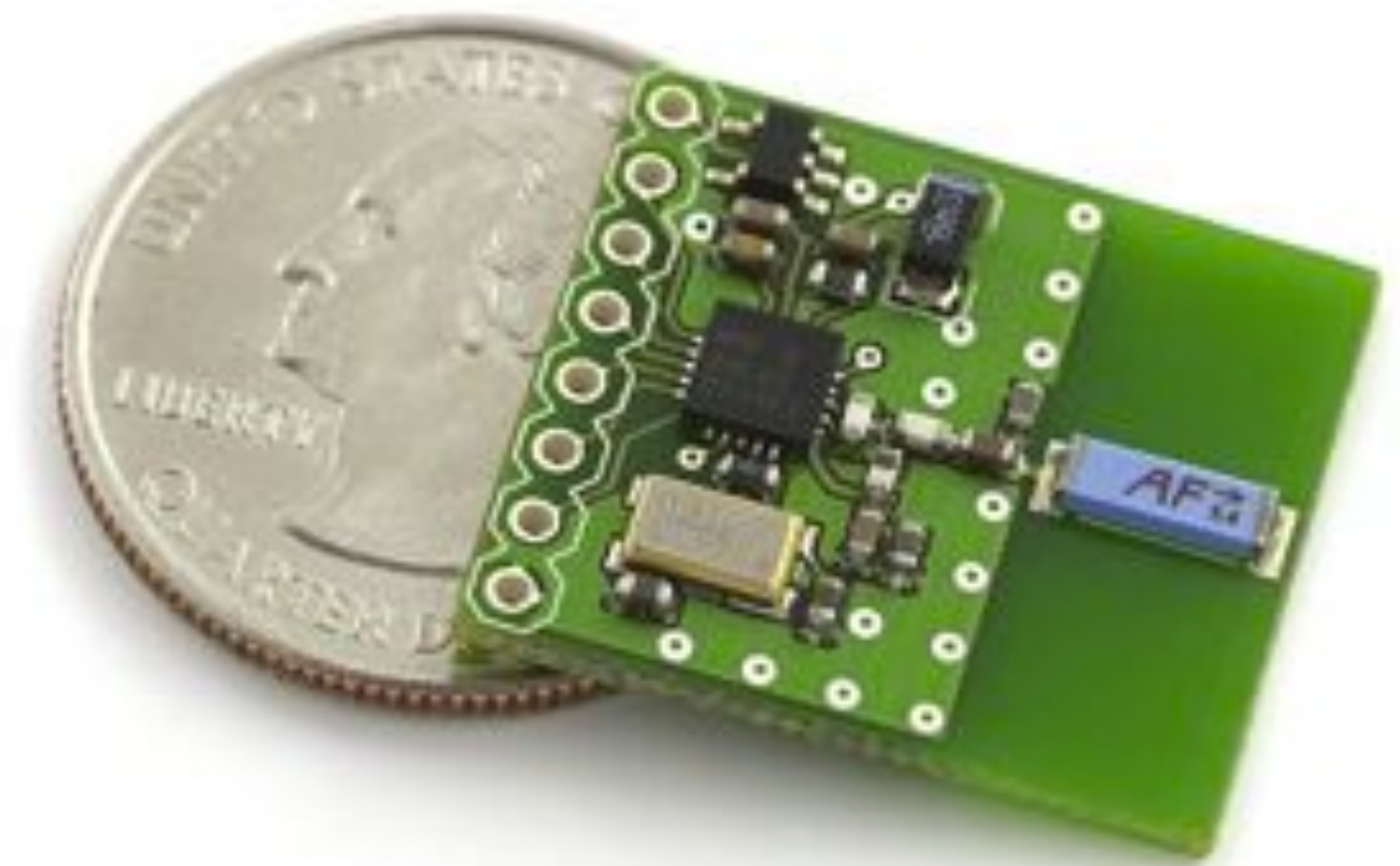
Wireless Communication

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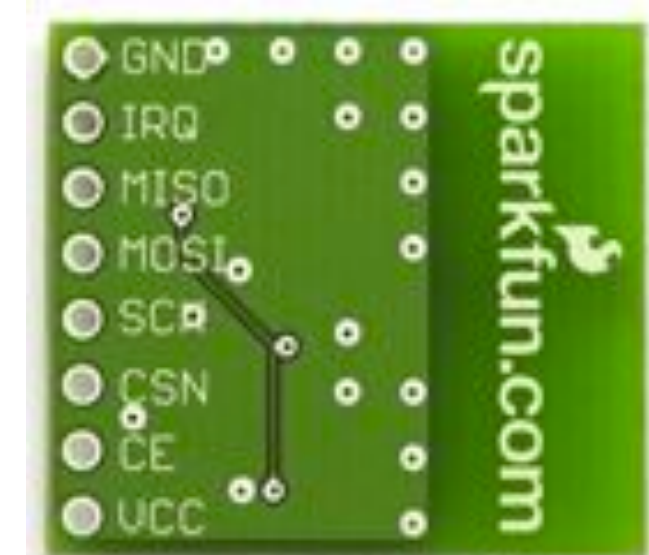
nrf24L01+ Module with Chip Antenna

- breakout of nrf24L01+ 2.4 GHz transceiver
- built in antenna
- SPI compatible
- 125 selectable channels
- 1-32 byte payload
- 6 Receiving Data Pipes



Pin Overview

- CSN - tells chip to begin listening (active low)
- SCK - SPI serial clock
- MISO - Master In, Slave Out
- MOSI - Master Out, Slave In
- IRQ - Interrupt (active low)
- CE - Chip Enable (different meanings depending on mode)
- VCC - Supply Voltage (+3.3 V)
- GND- Ground



Operating Modes

1. Power Down Mode

- least current consumption
- relatively long start up time

2. Standby Mode

- minimize current consumption while maintaining short start up times

3. Transmit Mode

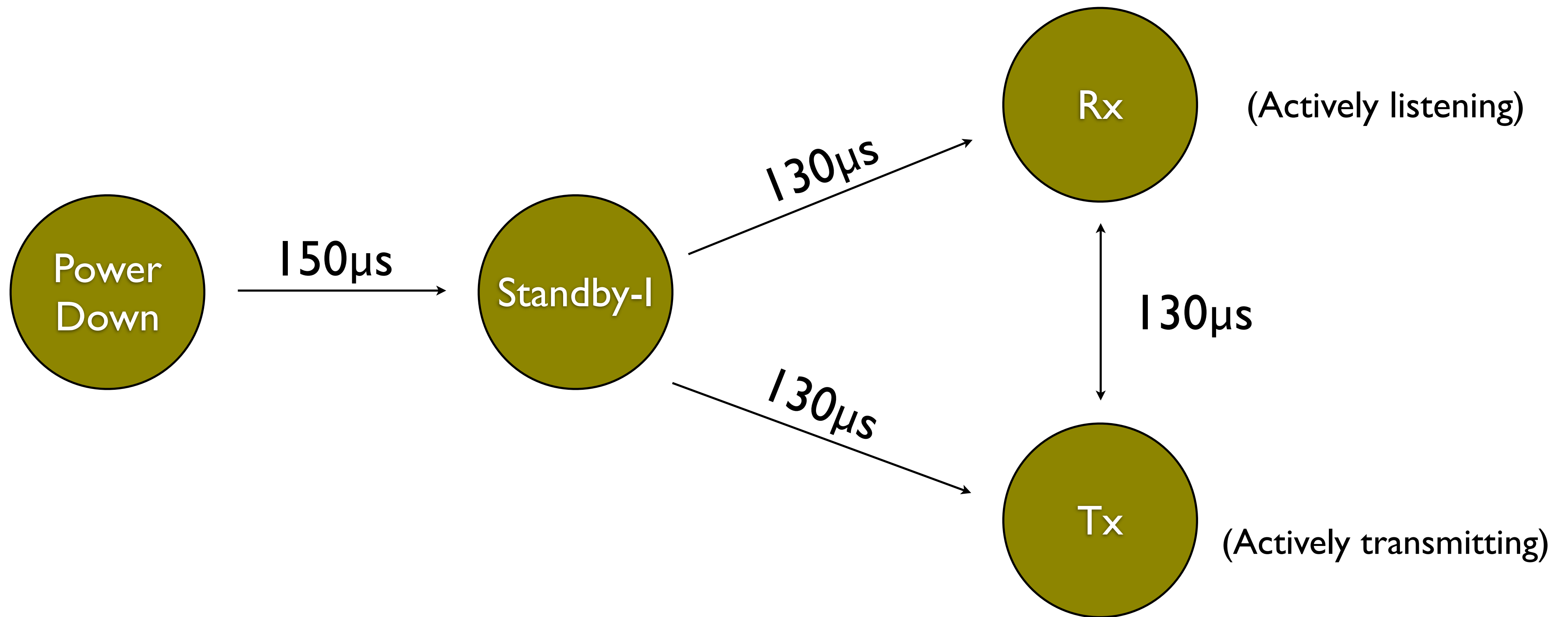
- only used when transmitting a packet
- never stay in longer than 4 ms

4. Receiver Mode

- constantly reads on-air data searching for a transmission

Mode Transition Times

(Hardware)



To go from Power Down mode to Rx/Tx mode, the nrf24L01+ **must** pass through Standby.

Air Data Rates & Channels

- The air data rate (how fast the chip sends/receives) can be **250kbps, 1 Mbps, or 2 Mbps**
 - lower data rates give a better receiver sensitivity and allow closer spacing between channel frequencies
 - higher data rates have less current consumption but require a larger spacing
- The nrfL2401+ can operate on channels between **2.4 GHz** and **2.525 GHz**
 - Channels while running at <1 Mbps require minimum spacing of **1 MHz**
 - Channels while running at 2 Mbps require minimum spacing of **2 MHz**

Air Data Rates & Channels

- So this allows for:
 - about 125 channels at < 1 Mbps
 - about 62 channels at < 2 Mbps
- Two nrf24L01+ chips must have the same channel and air data rate in order to communicate.

Addresses

- Every wireless transmission is preceded by the address of the receiver it is intended for
- A receiver will ignore transmissions that do not contain its address
- Addresses can be 3, 4 or 5 bytes long
- Addresses are user definable, so different receivers can share the same address if desired

Sample Transmission



Actual Data

Intended receiver

Cyclic Redundancy Check

Signal start of transmission

Payloads

- The payload is the actual data you are trying to send in your wireless transmission
- The wireless chips can handle payload sizes from 1-32 bytes
- A receiver will not recognize a transmission unless it is set to the correct payload

Setting up the nrf24L01.c library

- Available from www.DIYembedded.com
- To use:
 - define necessary pin registers and masks in nrf24L01.h
 - implement `spi_send_read_byte()`

Initialize SPI

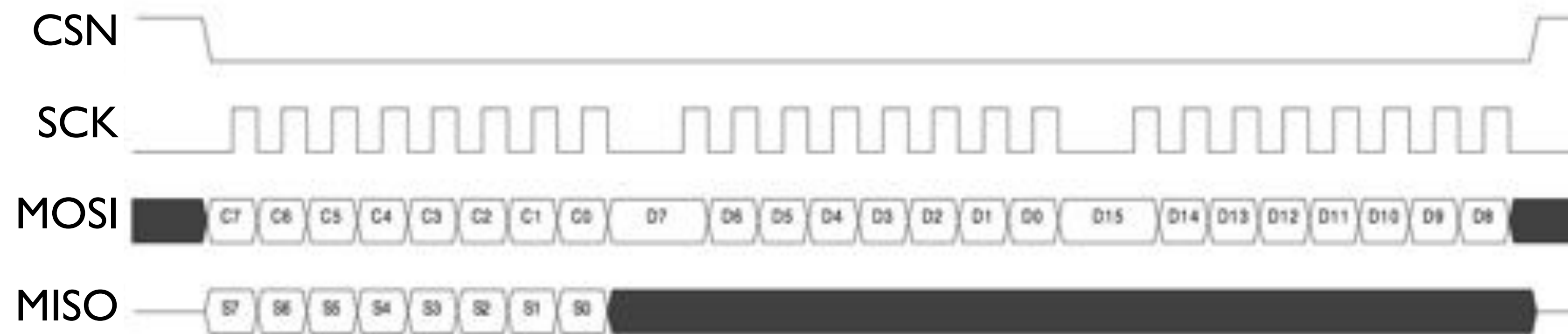
```
SpiInitDevice(1,1,0,0);
```

```
void SpiInitDevice(int chn, int isMaster, int frmEn, int frmMaster) {  
  
    unsigned int config = SPI_CON_MODE8|SPI_CON_SMP|SPI_CON_ON; // SPI configuration byte  
    if(isMaster)  
    {  
        config|=SPI_CON_MSTEN;  
    }  
    if(frmEn)  
    {  
        config|=SPI_CON_FRMEN;  
        if(!frmMaster) {  
            config|=SPI_CON_FRMSYNC;  
        }  
    }  
    SpiChnOpen(chn, config, 4); // divide fpb by 4, configure the I/O ports.  
}
```

Setting up the nrf24L01.c library

```
unsigned char spi_send_read_byte(unsigned char byte) {  
  
    char txData, rxData; // transmit, receive characters  
    int chn = 1; // SPI channel to use (1 or 2)  
  
    txData = byte; // take inputted byte and store into txData  
    SpiChnPutC(chn, txData); // send data  
    rxData = SpiChnGetC(chn); // retrieve over channel chn the  
    received data into rxData  
  
    return rxData;  
}
```

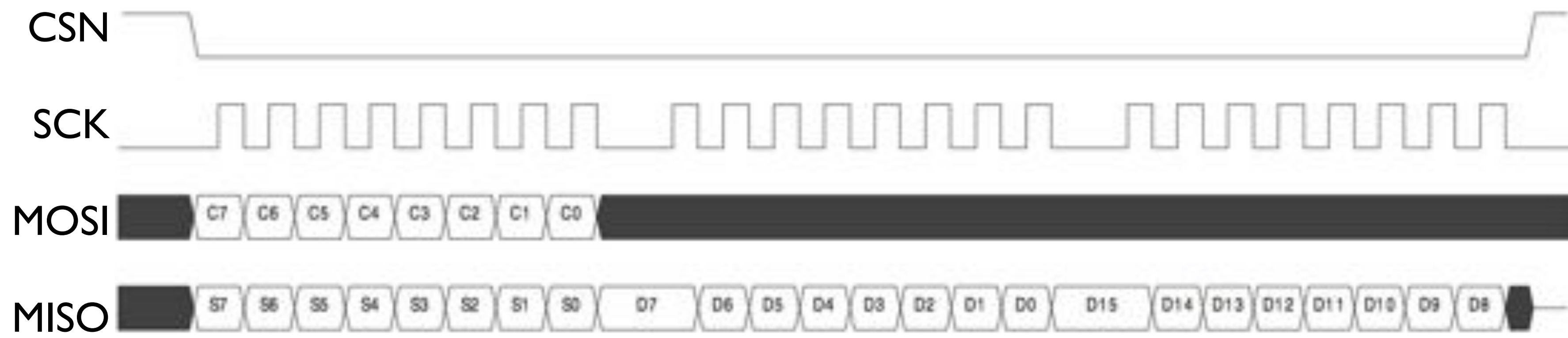
Sending an SPI Command



SPI Write

Cx- command bit
Sx- status register bit
Dx - data bit

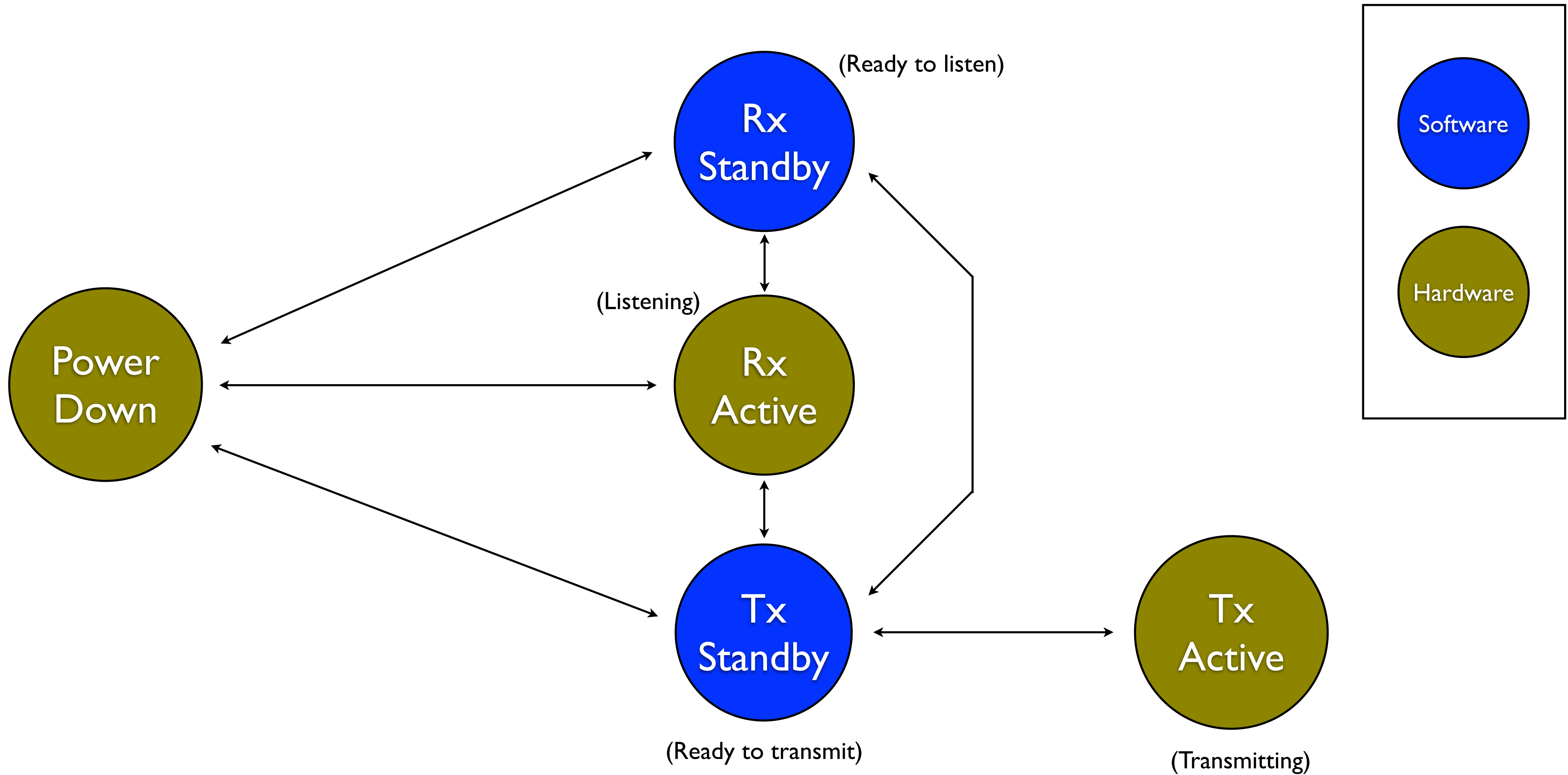
Sending an SPI Command



SPI Read

Cx- command bit
Sx- status register bit
Dx - data bit

Modes in the nrf24L01 + Library



Initializing the nrf24L01 +

1. `nrf24L01_initialize(...)`

- most control; lets you specify every register
- 21 arguments

2. `nrf24L01_initialize_debug(bool rx, unsigned char payload_width, bool aa_on)`

- lets you specify Tx/Rx, payload width, and whether or not to turn on auto-acknowledge
- everything else is set to default
- limits you to using pipe 0
- Channel = 2.403 GHz

Using the Library (Tx)

```
bool is_rx = false; //receiver?
int width= 1; //payload width
bool auto_ack = false; //auto acknowledge on?
nrf24l01_initialize_debug(is_rx, payload_width, auto_ack);
char data = 'a';
nrf24l01_write_tx_payload(&data, width, true); //transmit

//wait until it has been transmitted
while(!(nrf24l01_irq_pin_active() && nrf24l01_irq_tx_ds_active()));
nrf24l01_irq_clear_all(); //clear all interrupts
```

Using the Library (Tx)

Transmitting Payloads >1

```
bool is_rx = false; //receiver?

int width= 10; //payload width

bool auto_ack = false; //auto acknowledge on?

nrf24l01_initialize_debug(is_rx, payload_width, auto_ack);

char data[width];

/. . . Fill Array . . ./

nrf24l01_write_tx_payload(data, width, true); //transmit

//wait until it has been transmitted

while(!(nrf24l01_irq_pin_active() && nrf24l01_irq_tx_ds_active()));

nrf24l01_irq_clear_all(); //clear all interrupts
```

Using the Library (Tx)

Transmitting Payloads >1

- Your payload width can be shorter than size of the data array, but not bigger
- So if you plan on changing the payload, best practice is to initialize data array to a length of 32
- If you change the payload, you must re-initialize the nrf24L01+ before the new payload is recognized

Using the Library (Rx)

```
bool is_rx = true; //receiver?
int width= 1; //payload width
bool auto_ack = false; //auto acknowledge on?
nrf24l01_initialize_debug(is_rx, payload_width, auto_ack);
//wait until a packet has been received
while(!(nrf24l01_irq_pin_active() && nrf24l01_irq_rx_dr_active()));

nrf24l01_read_rx_payload(&data, width); //read into data variable
nrf24l01_irq_clear_all(); //clear all interrupts
```

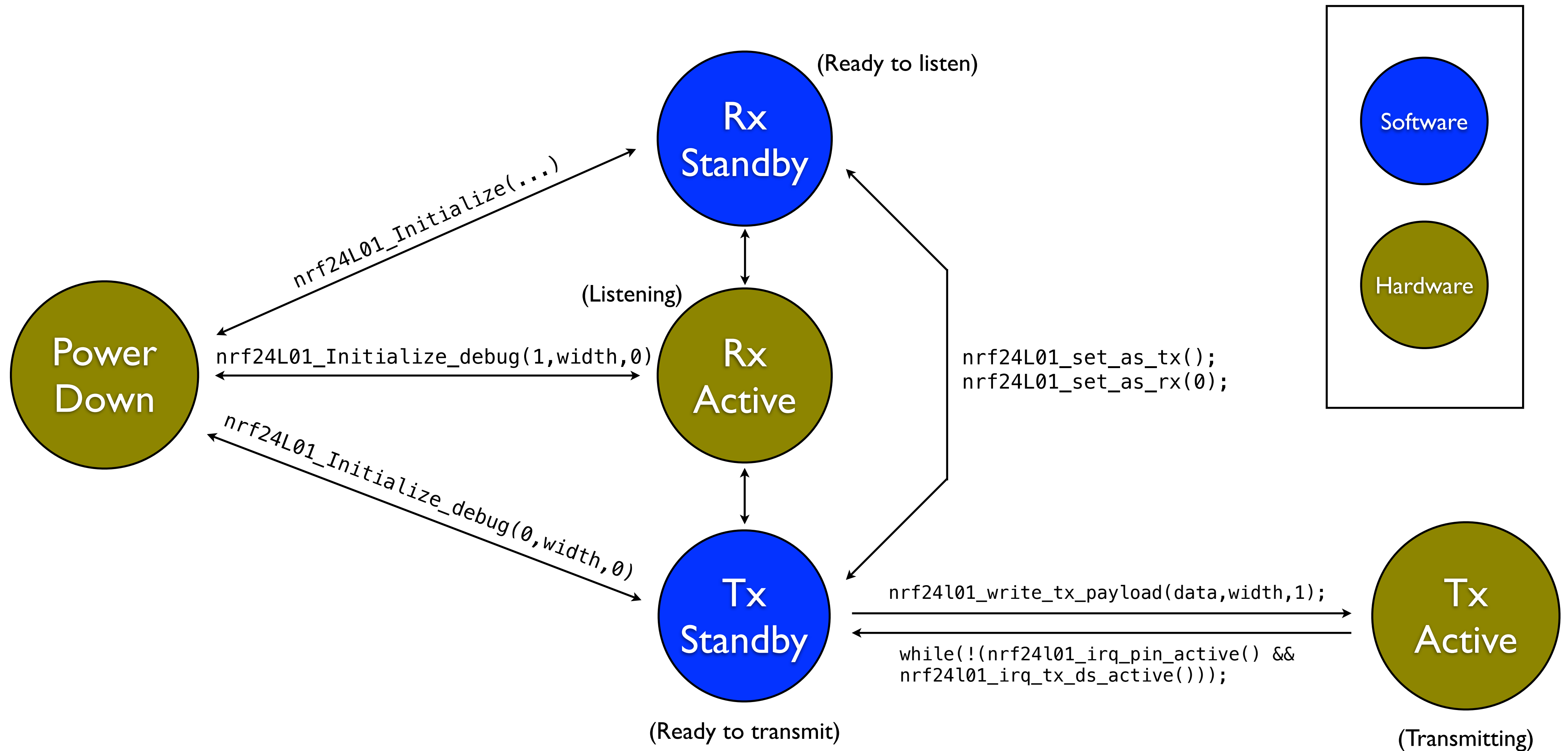
Using the Library (Rx)

Receiving Payloads >1

```
bool is_rx = true; //receiver?
int width= 10; //payload width
bool auto_ack = false; //auto acknowledge on?
nrf24l01_initialize_debug(is_rx, payload_width, auto_ack);
char data[width];
//wait until a packet has been received
while(!(nrf24l01_irq_pin_active() && nrf24l01_irq_rx_dr_active()));

nrf24l01_read_rx_payload(data, width); //read into data array
nrf24l01_irq_clear_all(); //clear all interrupts
```

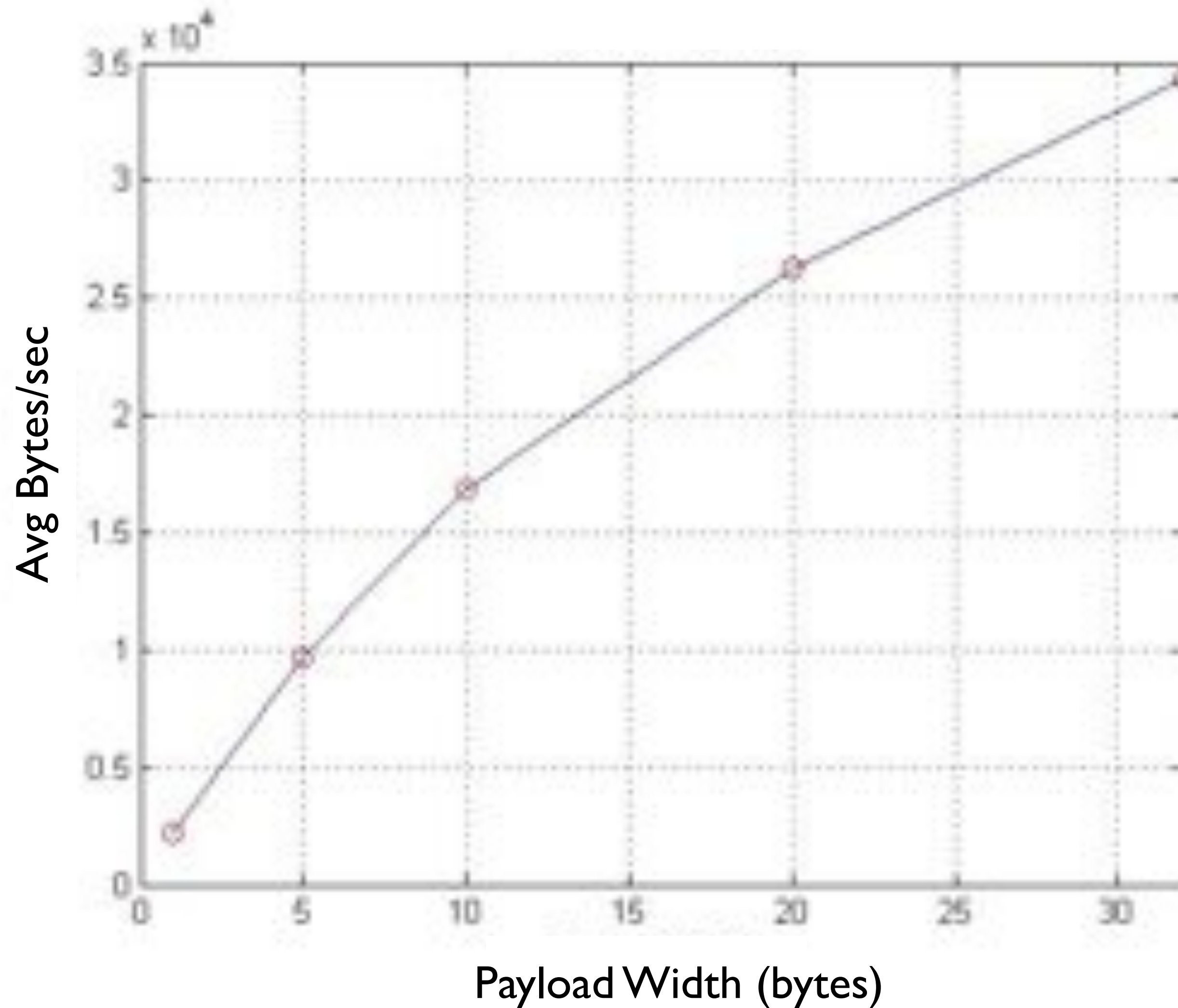
Modes in the nrf24L01 + Library



Helpful Functions

- `nrf24l01_power_down();`
- `nrf24l01_set_as_rx(bool rx_active_mode);`
 - change to Rx mode (active if true), keeping everything else constant
- `nrf24l01_set_as_tx();`
 - change to Tx Standby mode (keeping everything else constant)
- `nrf24l01_set_rf_ch(unsigned char channel);`
 - set RF channel to new value
- `nrf24l01_rx_pipe_enable(unsigned char rxpipenum);`
 - open a new receiver pipe
- Most functions (`receive_payload`, `transmit_payload`, etc.) return the current value of the status register

Payload Efficiency



Using Multiple Pipes

- Pipes essentially allow one nrf24L01+ chip to act as (up to) 6 different receivers at once
- Each active pipe needs a different address
- Different pipes may have a different payload width
- But all pipes must operate on the same channel (frequency)
- All pipes feed into the same 3 packet deep queue

Using Multiple Pipes

- Pipes 0 and 1 may have addresses completely different from each other
- But the addresses for pipes 2, 3 and 4 may only differ from that of Pipe 1 by the Least Significant Byte.

	Byte 4	Byte 3	Byte 2	Byte 1	Byte 0
Data pipe 0 (RX_ADDR_P0)	0xE7	0xD3	0xF0	0x35	0x77
Data pipe 1 (RX_ADDR_P1)	0xC2	0xC2	0xC2	0xC2	0xC2
	↓	↓	↓	↓	
Data pipe 2 (RX_ADDR_P2)	0xC2	0xC2	0xC2	0xC2	0xC3
	↓	↓	↓	↓	
Data pipe 3 (RX_ADDR_P3)	0xC2	0xC2	0xC2	0xC2	0xC4
	↓	↓	↓	↓	
Data pipe 4 (RX_ADDR_P4)	0xC2	0xC2	0xC2	0xC2	0xC5
	↓	↓	↓	↓	
Data pipe 5 (RX_ADDR_P5)	0xC2	0xC2	0xC2	0xC2	0xC6

Figure 13. Addressing data pipes 0-5

Using Multiple Pipes

```
status = nrf24l01_read_rx_payload(&data, 1);
pipe = nrf24l01_get_rx_pipe_from_status(status);

switch(pipe) {
case 0:
//process case 0
break;

case 1:
//process case 1
break;

case 2:
//process case 2
break;

default:
//process any other pipe
}
```